Cognitive social evaluations for multi-context BDI agents

Isaac Pinyol and Jordi Sabater-Mir

IIIA - Artificial Intelligence Research Institute CSIC - Spanish Scientific Research Council





2 The Repage Model and Multicontext BDI agents

- 3 Embedding Repage in a Multi-context BDI Agent
- 4 Conclusions and Future Work



Introduction and Motivation

2 The Repage Model and Multicontext BDI agents

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4 Conclusions and Future Work



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Reputation in Multi-Agent Systems (MAS)

Control of Interactions

Approaches to control interactions among agents:

- Security Approach: Integrity and authenticity of messages, agent's identity validation...
- Institutional Approach: Institutions observe agents' behaviors, and may punish them.
- Social Approach: Reputation mechanisms are here.

Mechanism to control agents' behavior in MAS when:

- Agents in open environments.
- Agents may have unknown intentions.
- Agents need to interact to each other to achieve their goals.



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• Several models have appeared in literature:

- Centralized approach: eBay, SPORAS, HISTOS ...
- **Distributed approach:** Regret, AFRAS, Schillo et al., Yu and Singh...
- Among them, **Repage:**
 - Computational system based on a cognitive theory of reputation.
 - Fundamental distinction between Image and Reputation
 - Image: Social evaluation that is believed by the agent.
 - Reputation: Social evaluation that has been spread by agents.



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Current state-of-the-art work

Focus on model definitions, not in the integration with the agent's architecture.

Global Objective

Integrate Repage information into a BDI agent architecture.



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The Repage System: Modeling Image and Reputation





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The Repage System: Modeling Image and Reputation Value Representation





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The Repage System: Modeling Image and Reputation

Image of A as a *seller* is



Implies that in the next direct interaction with A, agent **believes** that

- with a prob. of 0.3 it will be very bad
- with a prob. of 0.5 it will be **bad**
- with a prob. of 0.2 it will be **neutral**



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Definition

Let I be the set of context names, a MCS is formalized as $\langle \{C_i\}_{i \in I}, \triangle_{br} \rangle$

- $C_i = \langle L_i, A_i, \Delta_i \rangle$, where L_i is a formal language with its syntax and semantics, A_i is a set of axioms and Δ_i the a set of inference rules.
- \triangle_{br} is a set of bridge rules.

Definition

Bridge rules are inference rules to exchange information between contexts:

$$\frac{C_{i_1}:\varphi_1,\ldots,C_{i_n}:\varphi_n}{C_{i_n}:\varphi_n}$$



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A Multi-Context BDI Agent Specification



Relation between attitudes: strong realism, realism and weak realism.

¹Source: Parsons et al. Agents that reason and negotiate by arguing. Journal of MACSIC Logic and Computation, 8(3):261-292,1998. Page 272

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Embedding Repage in a Multi-context BDI agent



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General Features

- Lukasiewicz Logic (many-valued logic): So, predicates become fuzzy, and attitudes are graded.
- Dynamic Logic: $[\alpha]\varphi$, after executing action α , the formula φ holds.

²Based on: Casali *et al.* Graded models for BDI agents. *Proceedings of CLIMA WA-CSIC* Pages 18-33. 2004

Belief Context

Belief Context

- Crisp: If $\varphi \in L_D$ then $\varphi \in BC$
- **B-Modal**: Modal operator B over **crisp** formulas, together with a truth constant \overline{r} where $r \in [0, 1]$. Then:
 - If $\varphi \in L_D$ then $B\varphi \in BC$
 - If $r\in[0,1]$ then $\overline{r}\in BC$
 - If α, β ∈ BC then α →_L β and α ∧_L β ∈ BC. Here, the connectives →_L and ∧_L (conjunction and implication of Lukasiewicz multi-valued logic).

Example

```
 \begin{array}{l} (B[buy(alice)](haveCar \wedge hasPaid(7500)), 1) \\ (B[buy(alice)]dT(0,1), .5) \\ (B[buy(alice)]dT(3,\infty), .2) \\ (B[buy(alice)]vgCar, .3) \\ (B[buy(alice)]regularCar, .4) \end{array}
```



Desire and Intention Context

Desire Context

- Generic Desires: $(D^+\varphi, \delta)$, $(D^-\varphi, \delta)$: Level of satisfaction/disgust if φ holds is δ .
- Realistic Desires: $(D^+[\alpha]\varphi, \delta)$: Expected level of satisfaction of φ if α is executed is δ .

Example

 $\begin{array}{l} (D^+(haveCar \wedge vgCar \wedge dT(0,1)), 0.9) \\ (D^+(haveCar \wedge goodCar \wedge dT(1,3)), 0.7) \\ (D^-dTime(3,\infty), 0.8) \\ (D^-(vbadCar \vee badCar \vee regularCar), 0.7) \end{array}$

Intention Context

• $(I[\alpha]\varphi,\gamma)$: Trade-off between expected satisfaction level of φ after executing α , and its cost.



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- Generic Desire $(D^+\varphi, d_{\varphi})$
- Belief about getting φ trough the action α : $(B([\alpha]\varphi), p_{\varphi})$
- **RESULT**: Realistic desire $(D^+[\alpha]\varphi, g(d_{\varphi}, p_{\varphi}))$

Example

 $\begin{array}{c} DC: (D^-dT(3,\infty), 0.8) \\ BC: (B[buy(alice)]dT(3,\infty), 0.2) \\ DC: (D^-[buy(alice)]dT(3,\infty), 0.16) \end{array}$



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Example

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- A positive realistic desire $(D^+[\alpha]\varphi,\delta)$
- All negative realistic desires over the same action α .

 $(D^{-}[\alpha]\psi_1,\delta_{\psi_1}),\ldots,(D^{-}[\alpha]\psi_n,\delta_{\psi_n})$

- **Cost** of the action α : $action(\alpha, c)$
- **RESULT:** Intention of getting φ through α : $(I[\alpha]\varphi, f(\delta \sum_{i=1}^{n} \delta_{\psi_i}, c))$

Example

 $\begin{array}{c} (D^+[buy(alice)](vgCar \wedge dT(0,1)), 0.3) \\ (D^-[buy(alice)]dT(3,\infty), 0.16) \\ (D^-[buy(alice)]vbadCar, 0.05) \\ action(buy(alice), 0.9) \\ \hline (I[buy(alice)](vgCar \wedge dT(0,1)), 0.494) \end{array}$



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 $\frac{IC: (I[\alpha]\varphi, i_{max})}{C: does(\alpha)}$ 4:

Example

 $\frac{(I[buy(alice)](vgCar \land dT(0,1)), 0.494)}{does(buy(alice))}$



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Grounding and Repage Context Direct Experience in RepAge



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- Image Predicate $Img(Ag, r, [v_1, v_2, ...])$
- Grounding discretization functions: $\varphi_1(r), \varphi_2(r), \ldots$
- Action associated to $r{:}~\phi(r)$

Example

 $\frac{Img(alice, seller(dTime), [0.2, 0.3, 0.5])}{(B[buy(alice)]dT(3, \infty), 0.2)} \\ (B[buy(alice)]dT(1, 3), 0.3) \\ (B[buy(alice)]dT(0, 1), 0.5)$



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Ending...



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- Incorporate Reputation (done)
- Implementation / Simulations
- Incorporate proactivity to solve cognitive dissonances.
- Argumentation.
- Ontology alignment.
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Thanks for you attention!



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